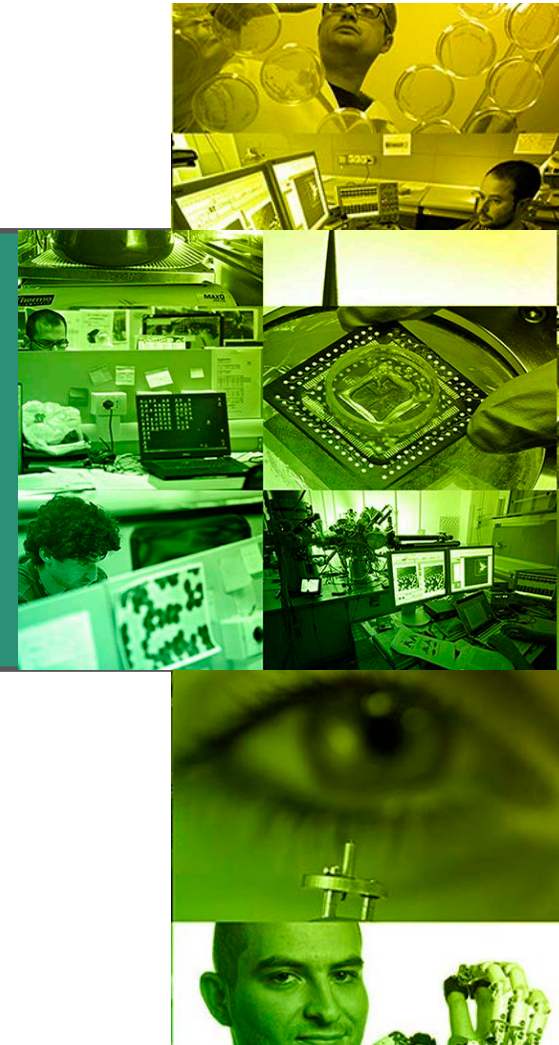


Istituto Italiano di Tecnologia

Evaluation exercises of an international research institute

Eleonora Palmaro

October 7, 2015



Technology with human touch

In this presentation

Background on Istituto Italiano di Tecnologia (IIT)

Output, Impact and Collaboration

Deep dive into Robotics



Istituto Italiano di Tecnologia

Technology with human touch

Who

- A scientific research institute

When

- Established in 2003
- Scientific activity started in 2006

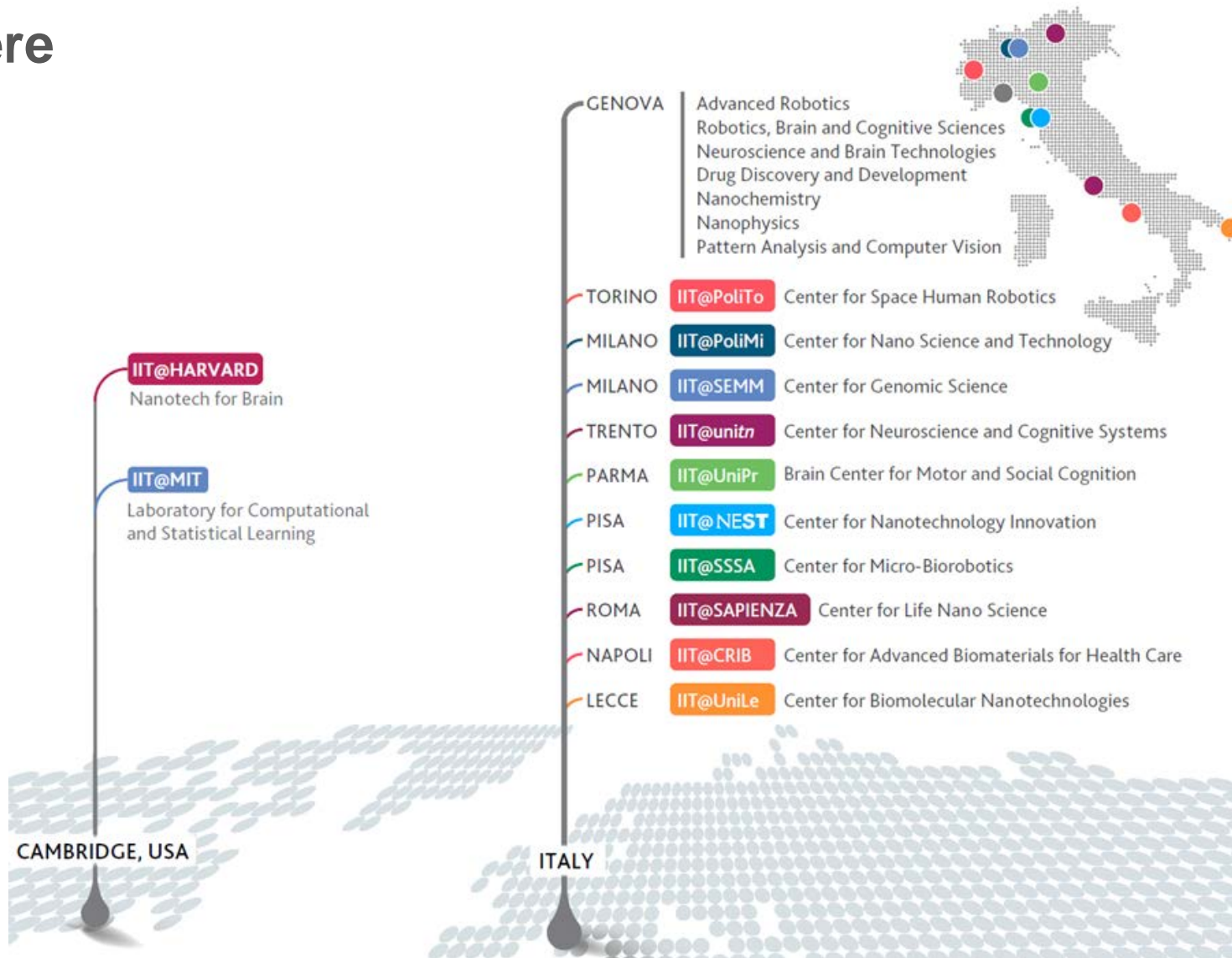
What

Twofold mission:

- Performing cutting edge research
- Transferring technology to the industrial system



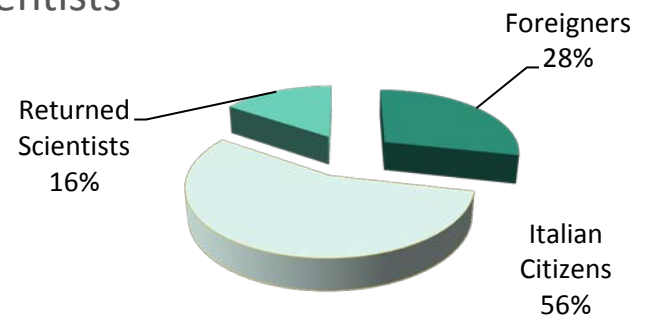
Where



Why international



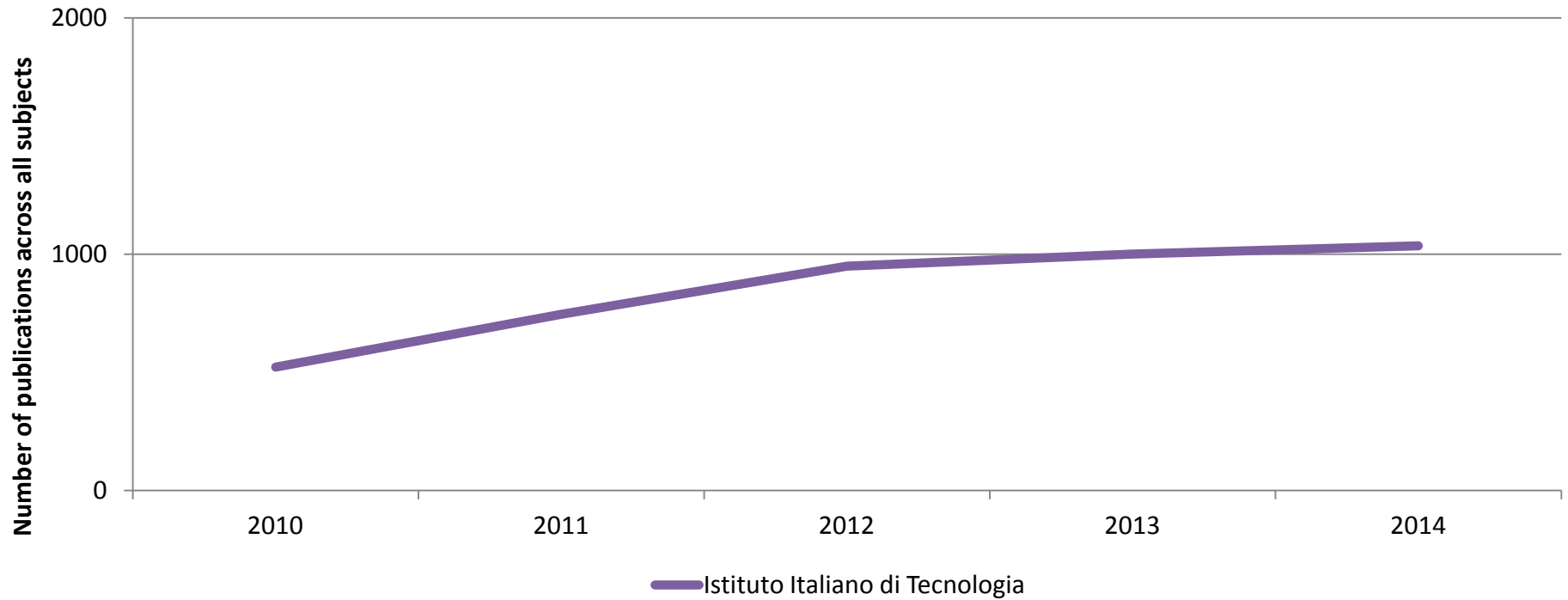
Scientists



Output, Impact and Collaboration

Technology with human touch

Research output



It is advisable to introduce peer institutes as benchmarks

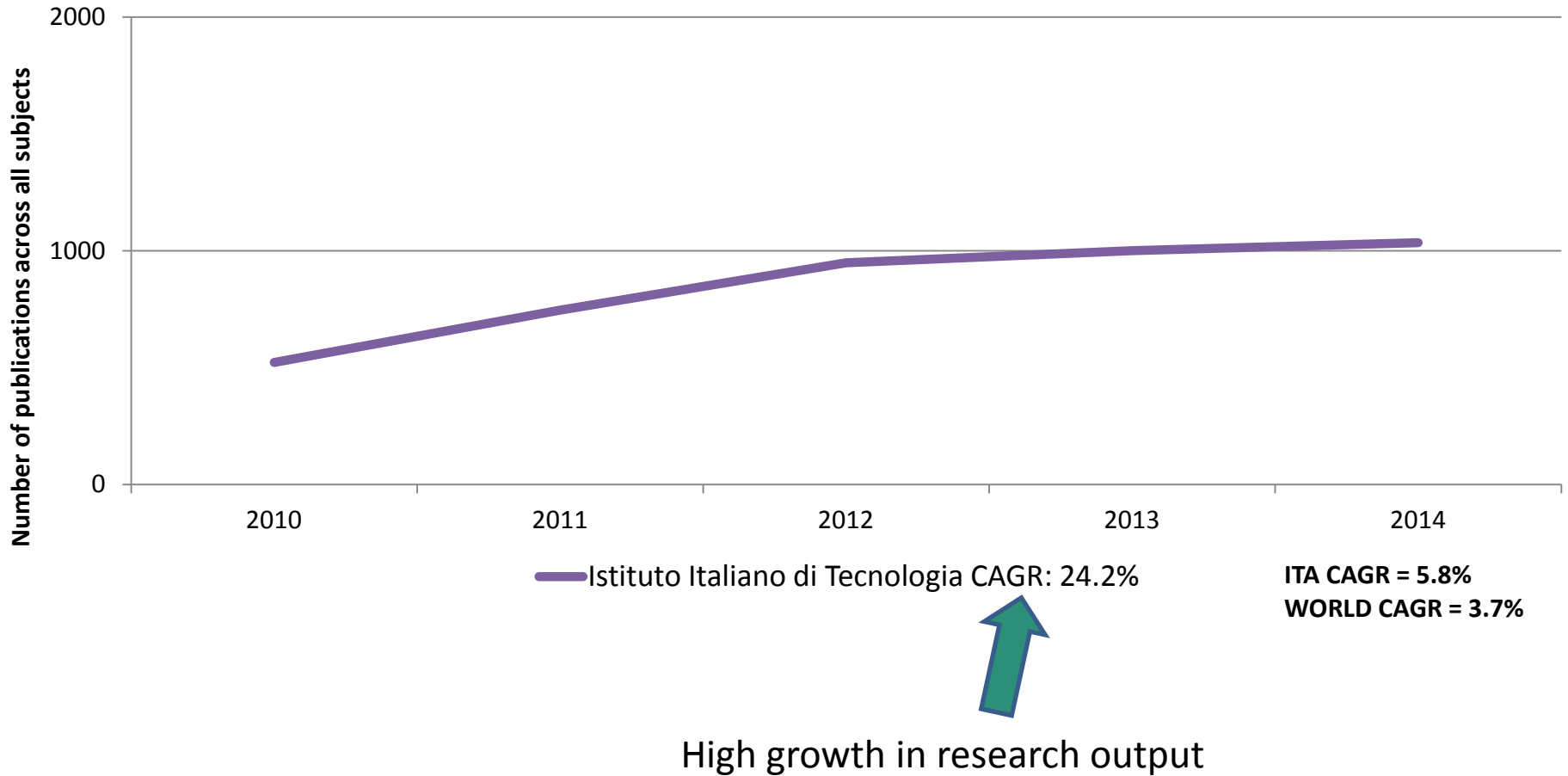
Compound Annual Growth Rate, CAGR

The year-over-year constant growth rate over a specified period of time. Starting with the first value in any series and applying this rate for each of the time intervals yields the amount in the final value of the series

$$\text{CAGR} = \left(\frac{\text{Ending Value}}{\text{Beginning Value}} \right)^{\frac{1}{\# \text{ of years}}} - 1$$

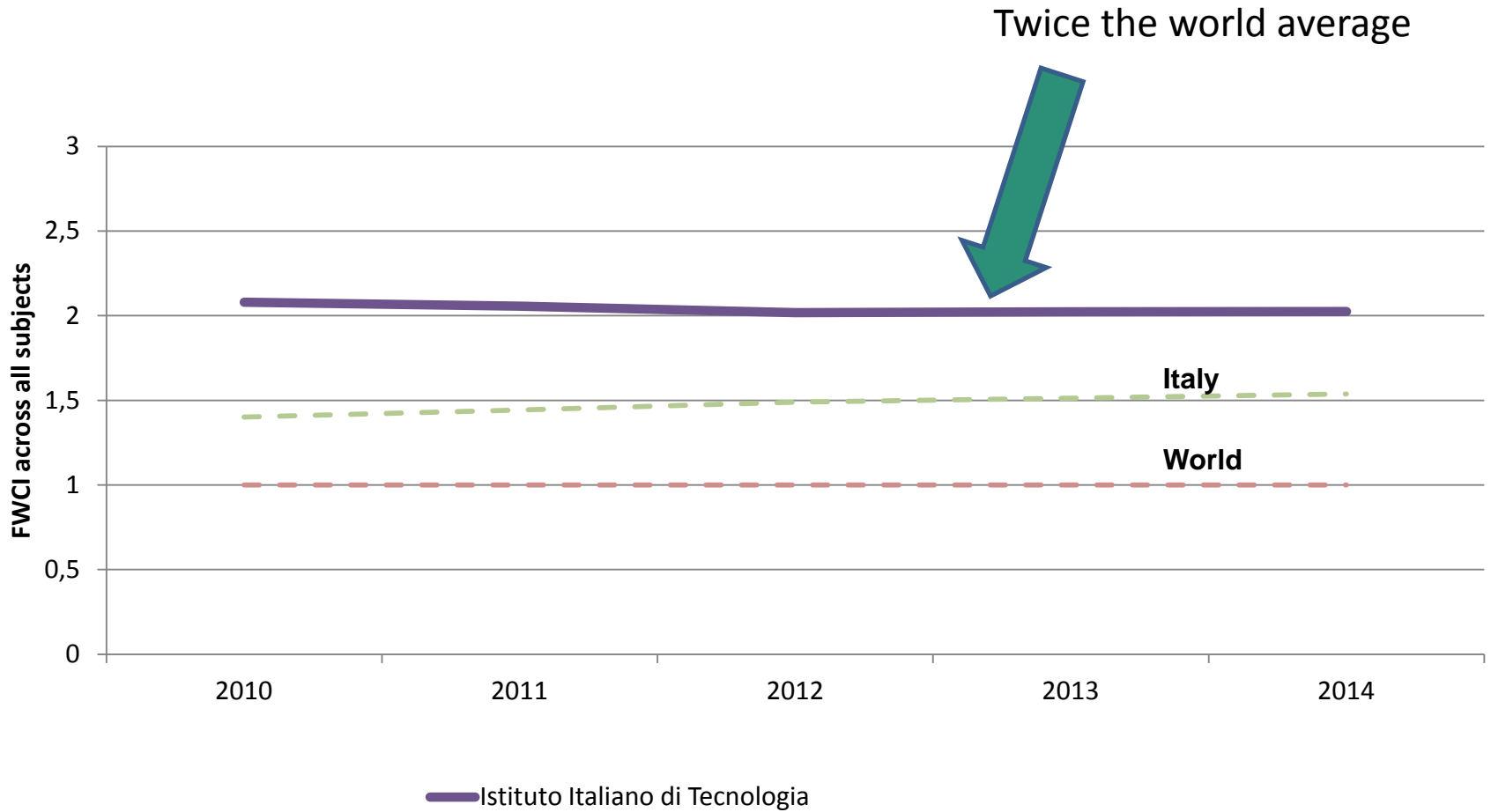
The report analyses Istituto Italiano di Tecnologia's research output, growth, impact, and excellence for the period 2010-2014. 2014 data are about 5% incomplete at the time of writing, due to standard publication delays and indexation timelines. Therefore output growth is calculated for 2010-2013 rather than 2010-2014. This slight incompleteness does not affect shares or impact indicators

Research output

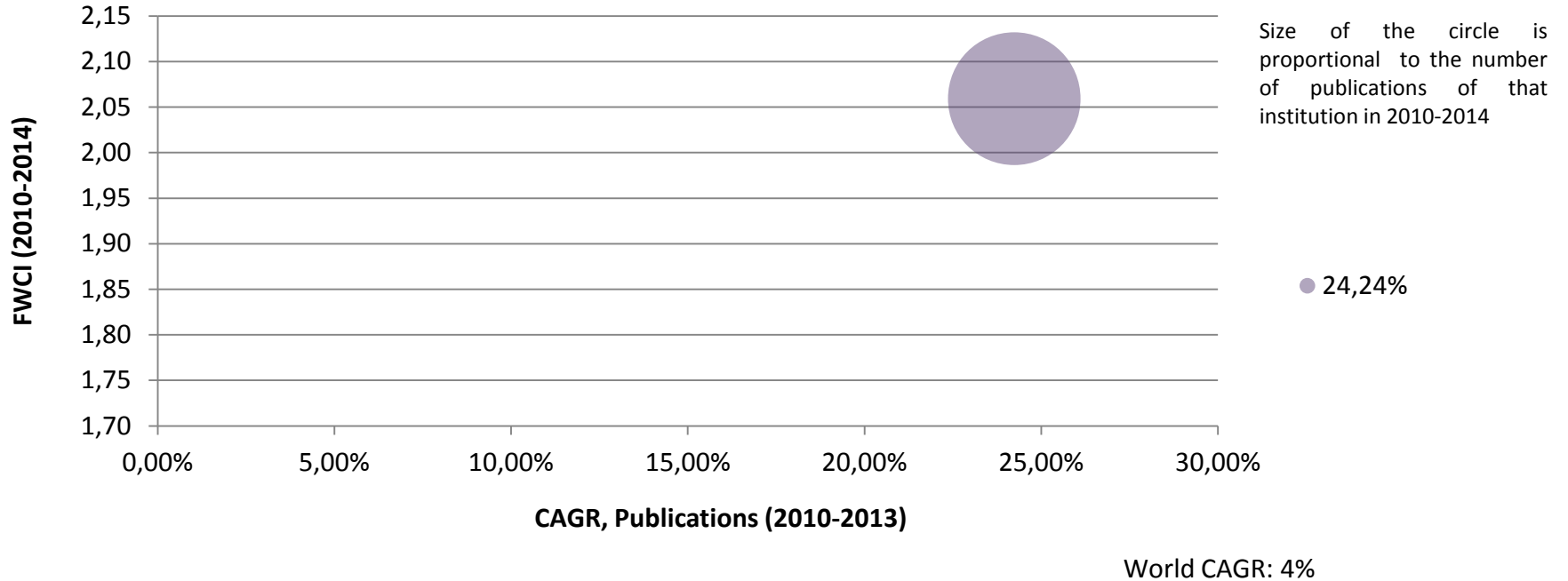


It is advisable to introduce peer institutes as benchmarks

Citation Impact



Output growth and impact

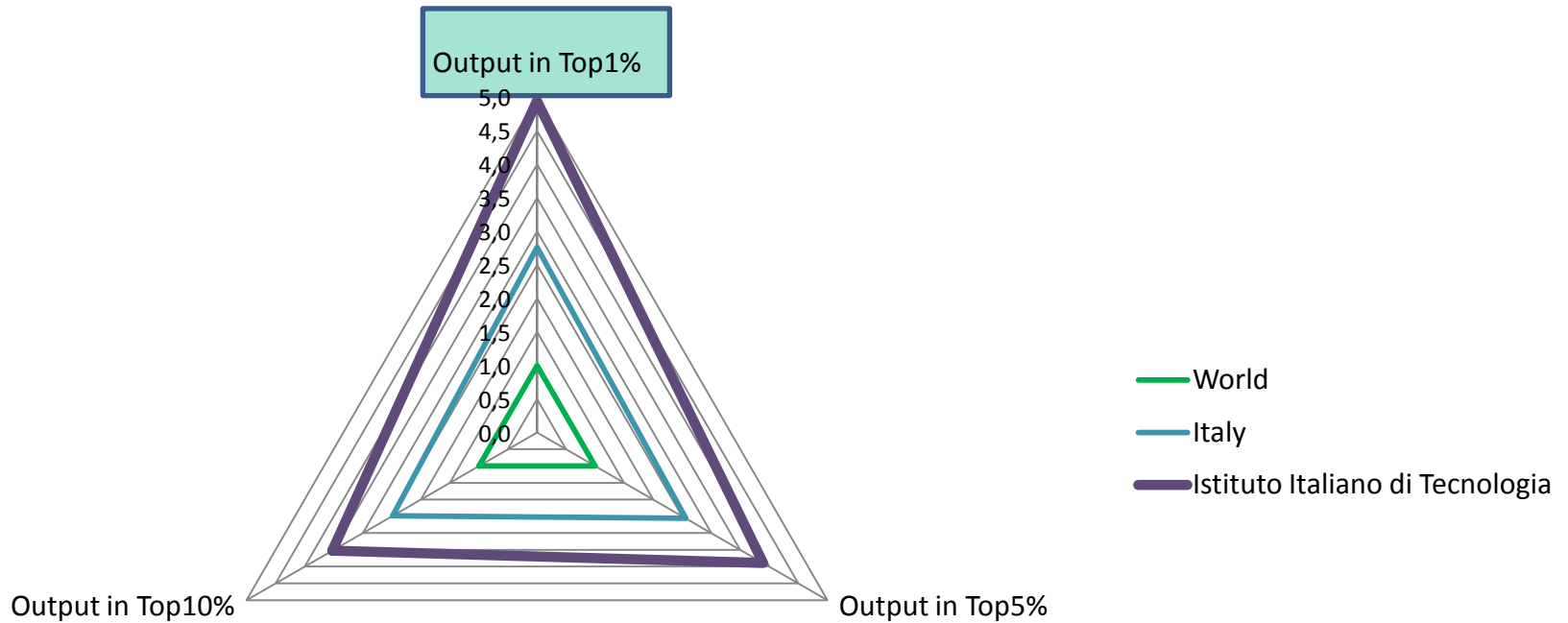


It is advisable to introduce peer institutes as benchmarks

Excellence

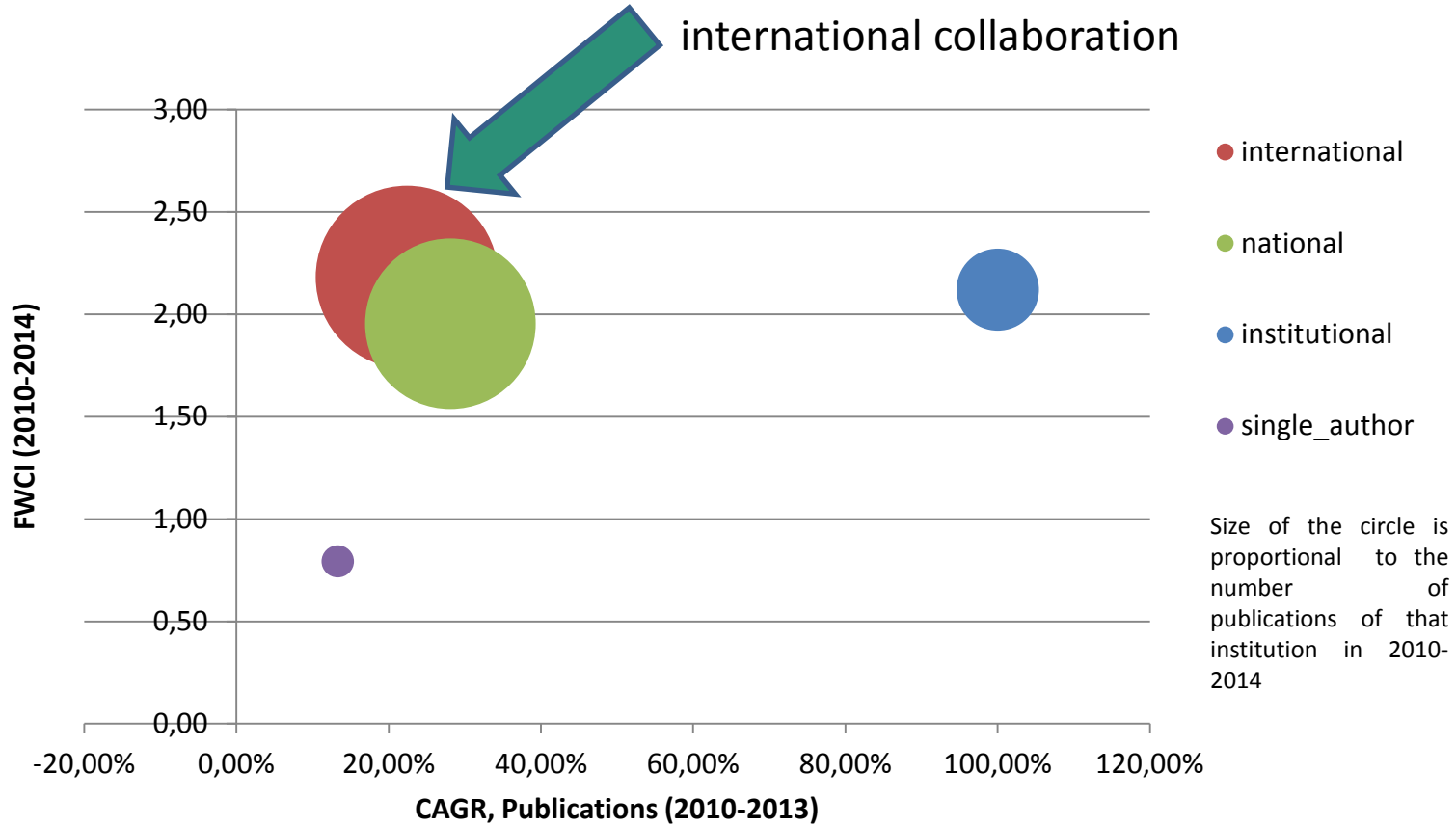
Istituto Italiano di Tecnologia

excellence in the highly cited spectrum of the publications



Collaboration

The highest impact is associated with the international collaboration



Key findings

PRODUCTIVITY



Volumes of outputs:
articles, reviews,
conference papers

IMPACT



FWCI,
an indicator
of mean citation impact

EXCELLENCE



Percentiles ,
highly cited articles
(top 1%, 5%, 10%)

EXCHANGE

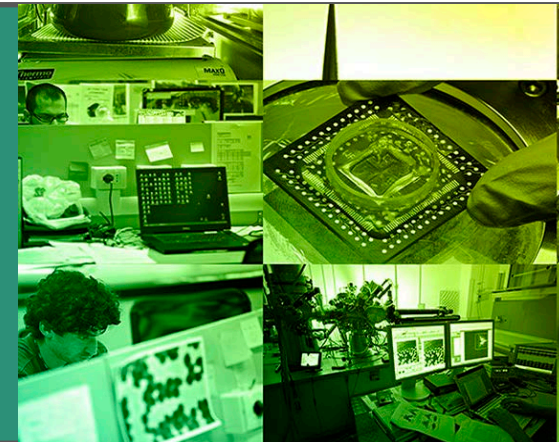


Collaboration ,
international, national,
institutional,
single_author

Importance of benchmarking

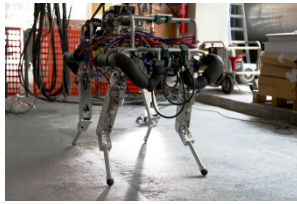


Deep dive into Robotics

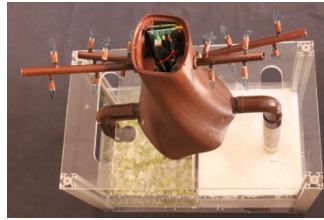


Technology with human touch

Matrix organization



Animaloids



Biomechanics

Plantoids

Commercial Domain

Perception Ability

Humanoids

Interaction Ability



Robotics

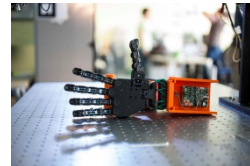
Civil Domain

Artificial Intelligence

Cognition

Healthcare

Mechatronics



Nanocomponents



Decisional Autonomy

Material Science

Adaptability

Cognitive ability

Human robot interaction



Subject classification

CUN areas, aree Consorzio Universitario Nazionale

UOA, Units of Assessment

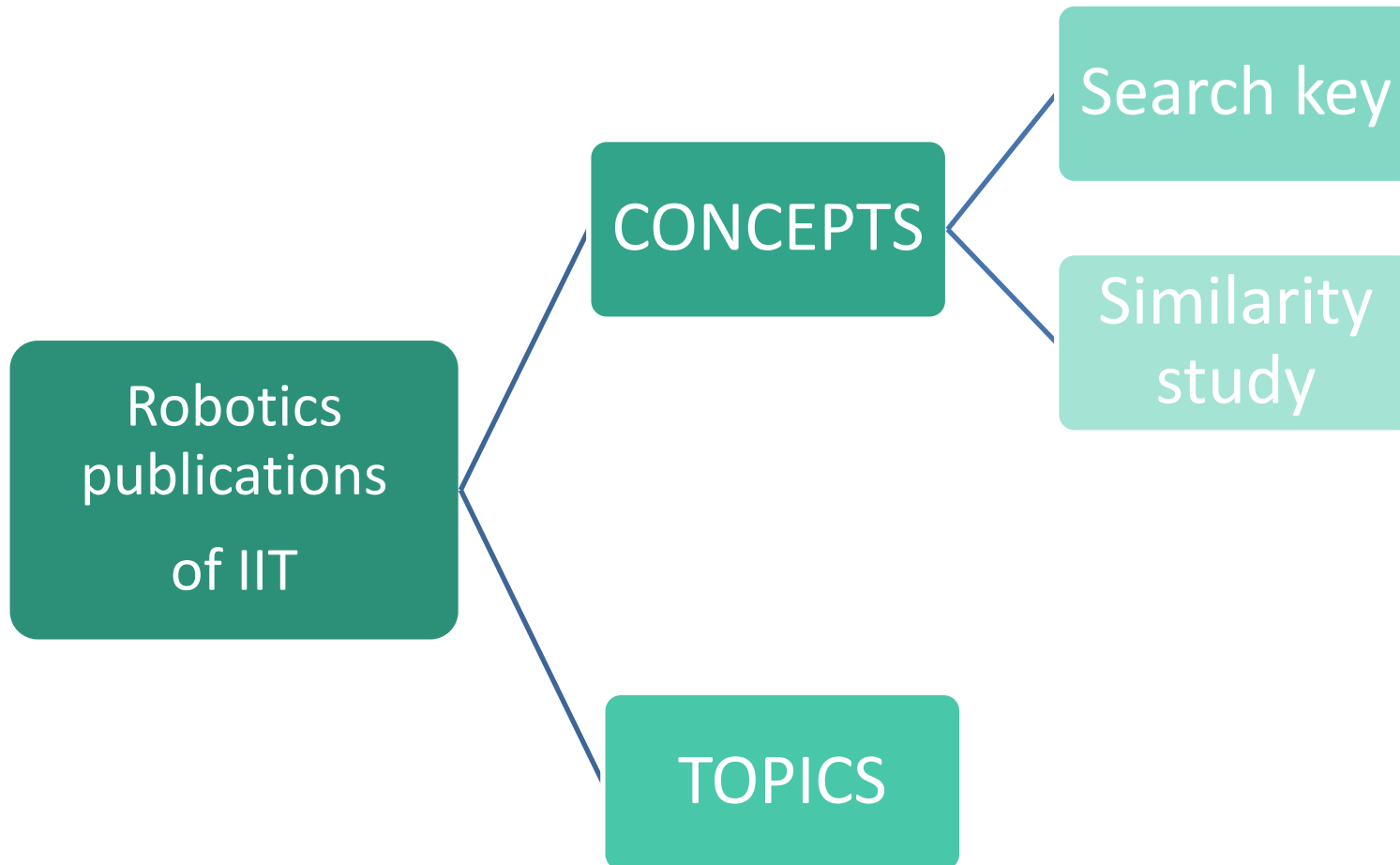
FOR, Fields of Research

FOS, Field of Science and Technology

ASJC, All Science Journal Classification

The rigidity of classification systems does not allow to capture new developments of areas of research and the interdisciplinarity

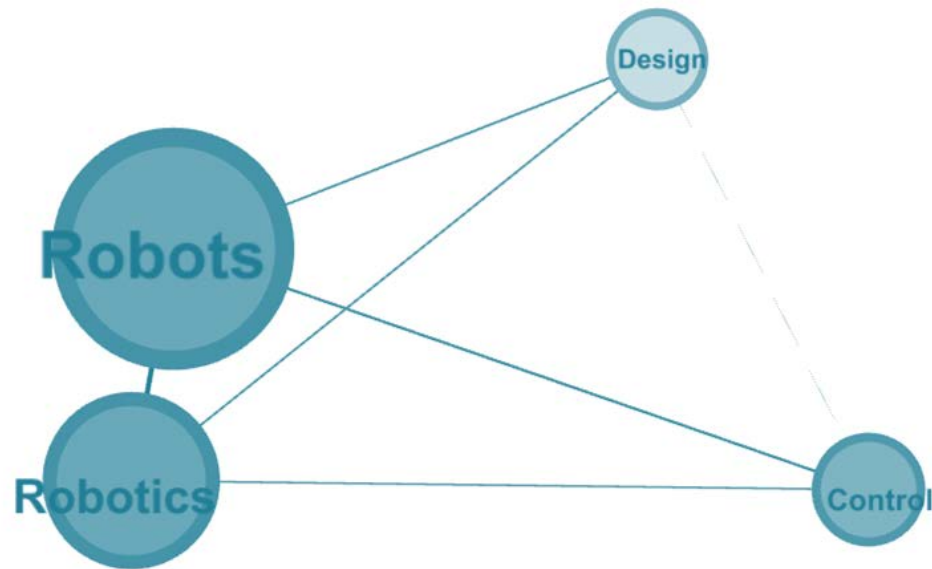
Content



Concepts

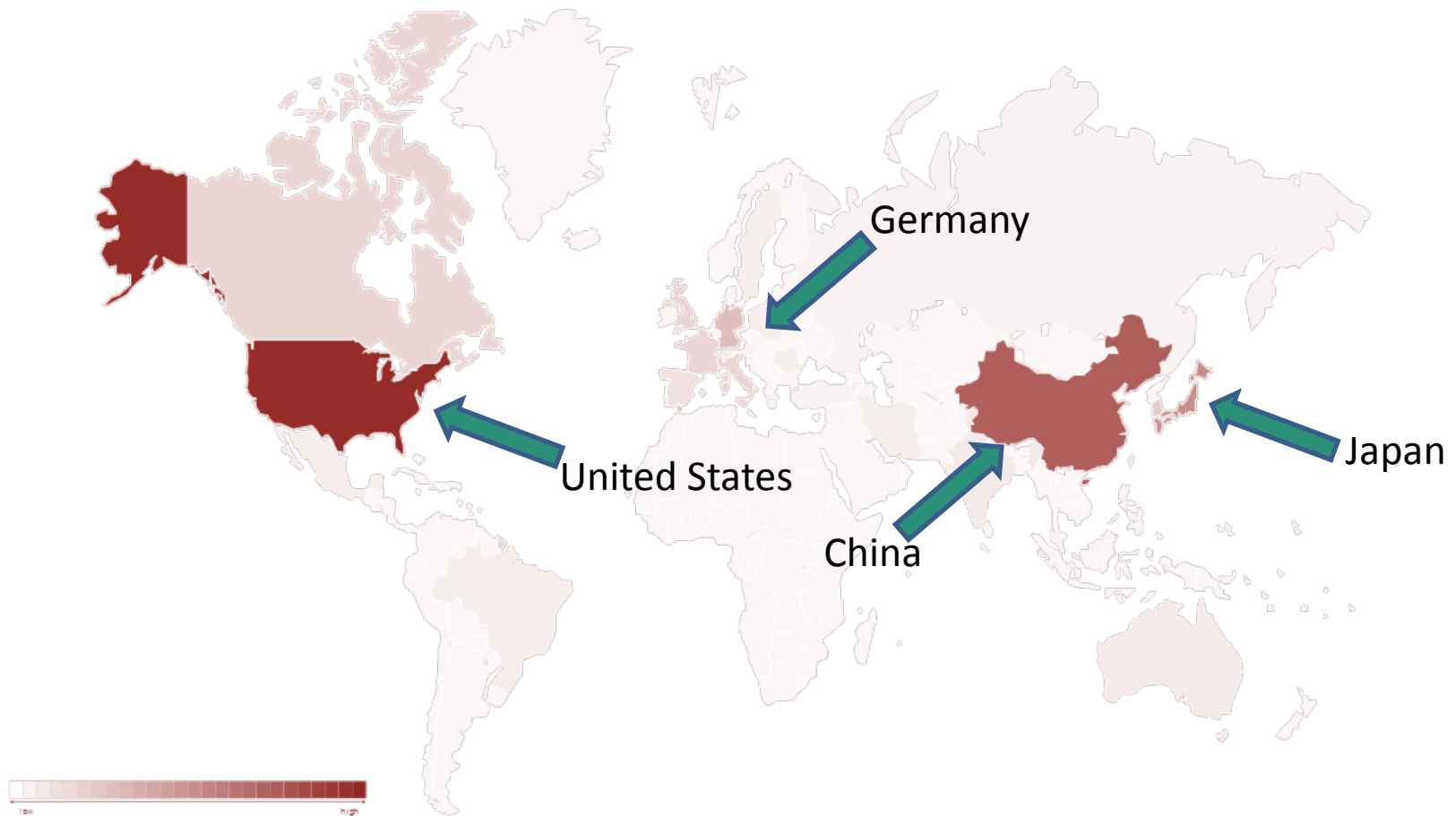
COMPENDEX

Engineering literature database
with over 17 million records
from 73 countries across 190 engineering
disciplines

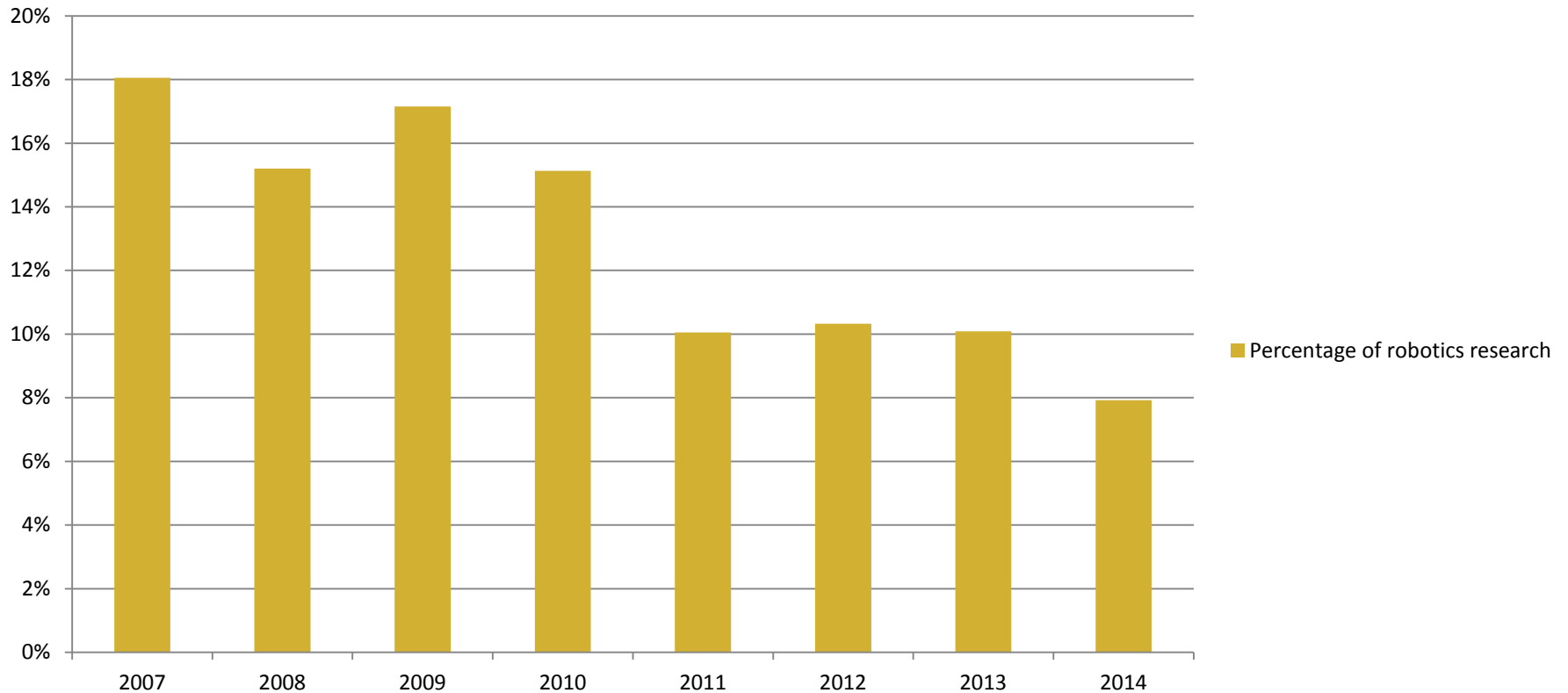


Search key in Solr-> robot* AND (design OR control)

Country distribution of robotics' publications



Istituto Italiano di Tecnologia



The trend shows the increase of the number of the research programs

Similarity study

The Jaccard coefficient measures similarity between finite sample sets, and is defined as the size of the intersection divided by the size of the union of the sample sets:

$$J(A, B) = \frac{|A \cap B|}{|A \cup B|}$$

Clusters

Gephi is an interactive visualization and exploration platform for all kinds of networks and complex systems

Concepts map

Physical human-robot interaction



Visual geometry and modelling



Machine Learning



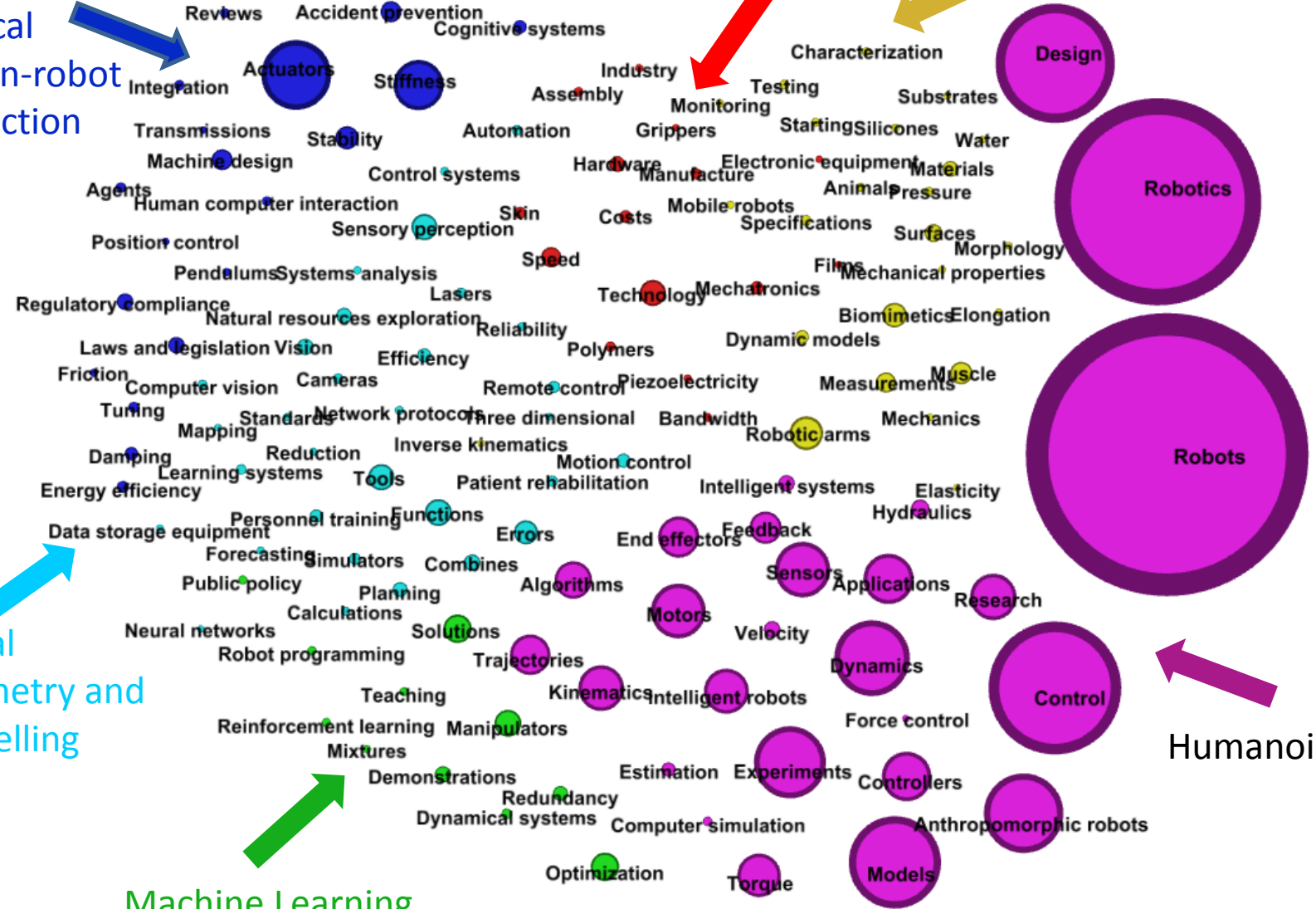
Nanomaterials



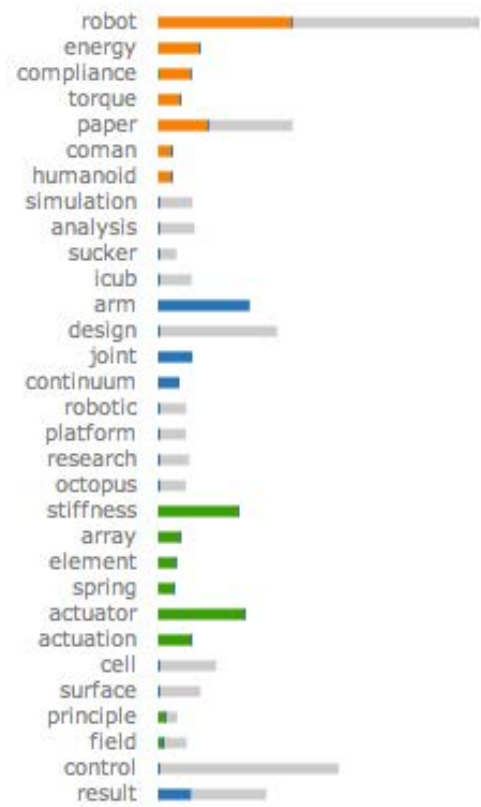
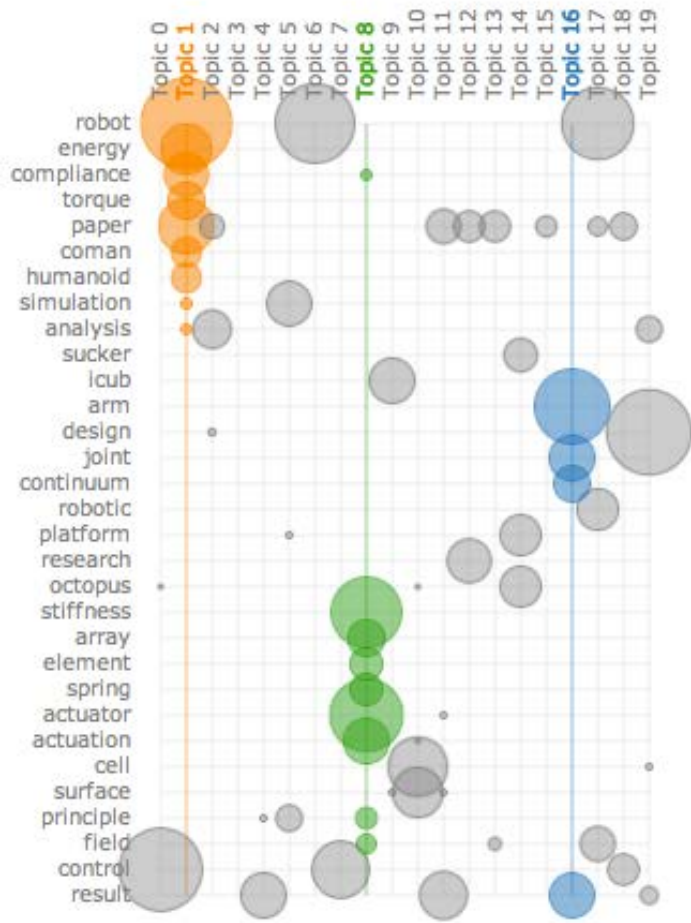
Rehabilitation



Humanoids



Topics



MALLET, MACHINE Learning for Language Toolkit

Roncone, A., Hoffmann, M., Pattacini, U., Metta, G. **Automatic kinematic chain calibration using artificial skin: Self-touch in the iCub humanoid robot** (2014) Proceedings - IEEE International Conference on Robotics and Automation, art. no. 6907178, pp. 2305-2312.

Li, Z., Vanderborght, B., Tsagarakis, N.G., Caldwell, D.G. **Human-like walking with straightened knees, toe-off and heel-strike for the humanoid robot iCub** (2010) IET Seminar Digest, 2010 (4), art. no. 0356, pp. 638-643.

Medrano-Cerda, G.A., Dallali, H., Brown, M., Tsagarakis, N.G., Caldwell, D.G. **Modelling and simulation of the locomotion of humanoid robots** (2010) IET Seminar Digest, 2010 (4), art. no. 0367, pp. 704-709.

Content

Advantages

Objective start point

Flexibility

More retrieval information

Limits

Absence of a standard methodology to define the research areas

Definition of the thresholds

Need of expert feedback

Next steps

Look at the concepts of the publications of each Principal Investigator to compare their performance with the other researchers of the field in the world

Explore more the topics methodology

Involve the researchers to check the results

Combine the content information with the bibliometric indicators

Thank you